

# Introduction to network flows

## Overview

- > Transport network and flows
- > Complete flows.
- > Maximum flows.
- > Ford-Fulkerson algorithm.
- > Multiflows and dynamic flows.

## Definition of a transport network and an $s$ - $t$ -flow

> A transport Network  $R=(G,u,s,t)$  consists in :

- A digraph  $G=(V,A)$ .
- A capacity function  $u : A \rightarrow \mathbb{R}^+$ .
- Two particular vertices  $s$  and  $t$  in  $V$  (resp. called *source* and *sink*).

> Let  $R=(G,u,s,t)$  be a transport network, we call  $s$ - $t$ -flow on  $R$  function  $f : A \rightarrow \mathbb{R}^+$  such that :

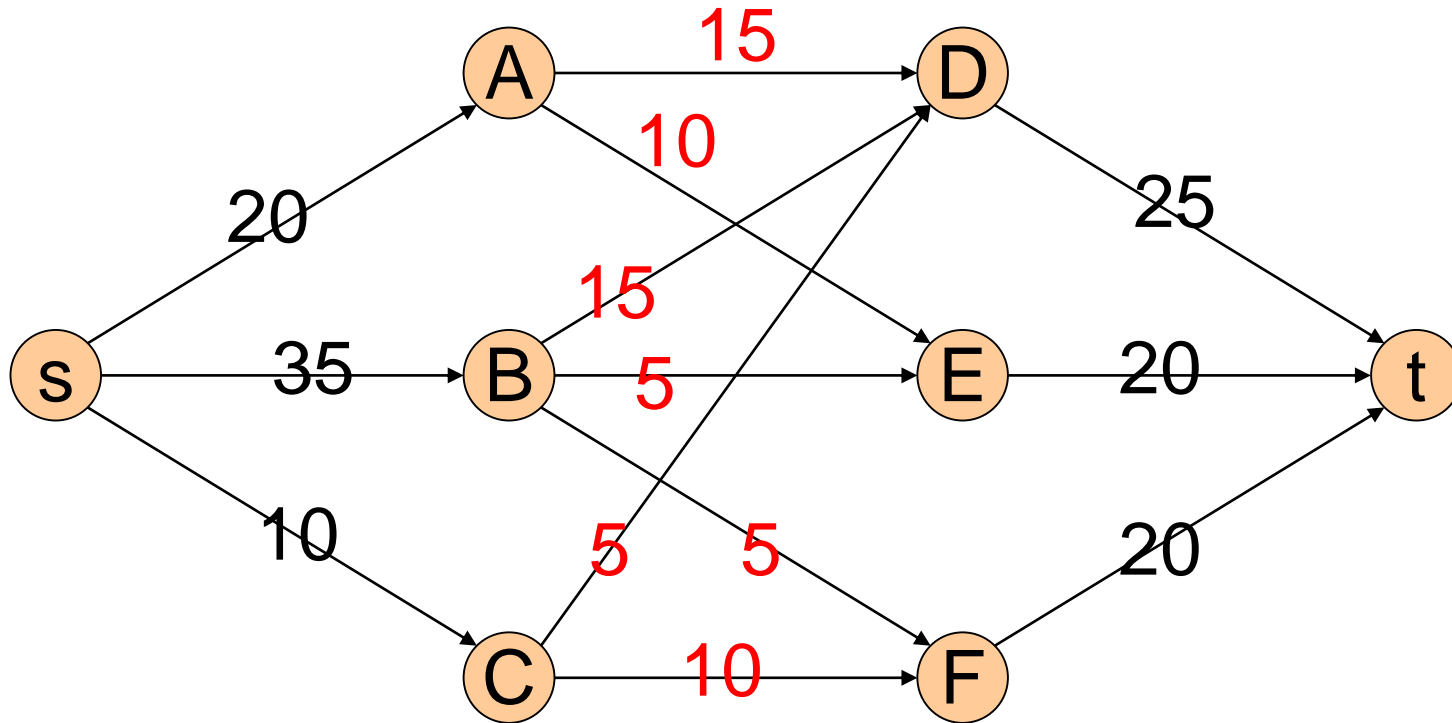
- $f(a) \leq u(a)$ , for all  $a \in A$ .
- $\sum_{a \in \delta^-(v)} f(a) = \sum_{a \in \delta^+(v)} f(a)$ , for all  $v \in V \setminus \{s,t\}$  (Kirchoff constraint).

# Example

> Three warehouses A, B, C, contain respectively 20, 35 et 10 tons of goods. There are demands of 25, 20 et 20 tons to destinations D, E and F. The unitary transportation costs are given in the following matrix. What would be the minimal cost transport plan ?

	D	E	F
A	15	10	0
B	15	5	5
C	5	0	10

# The associated transport network

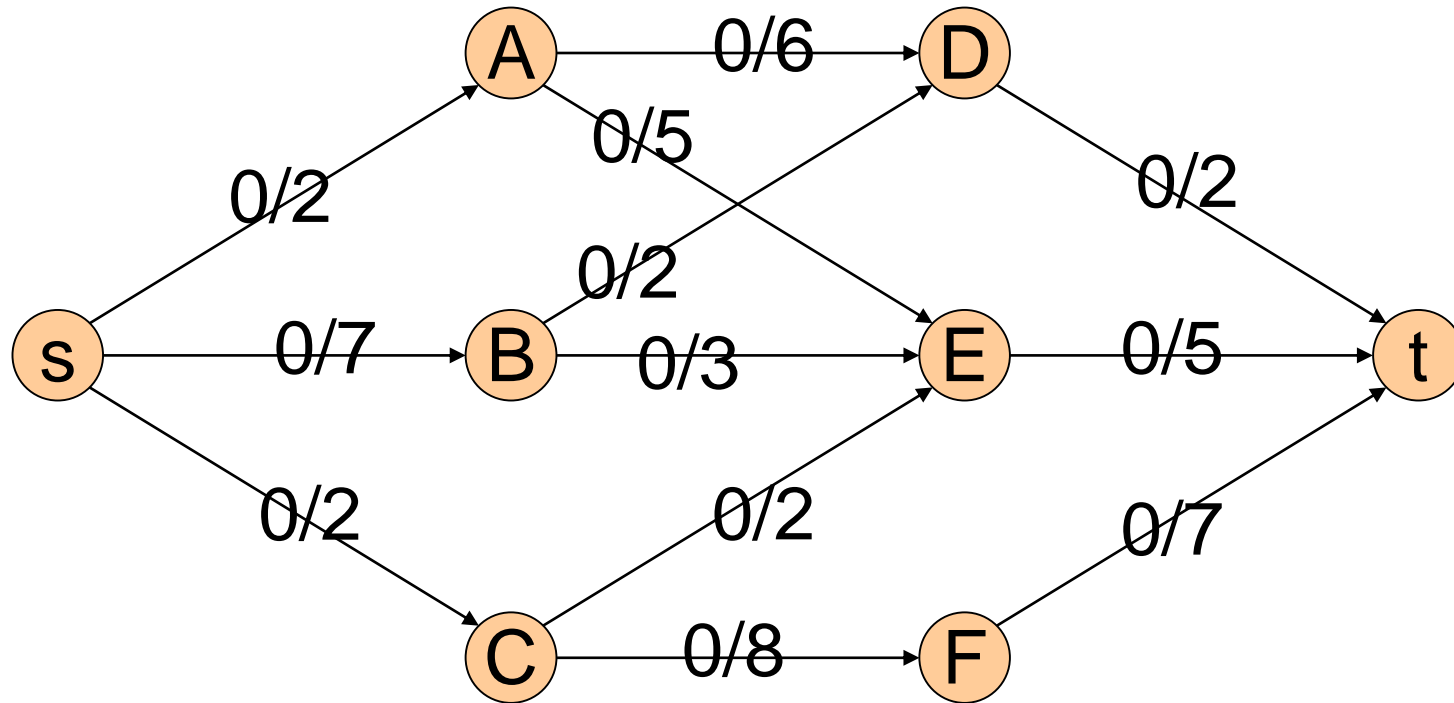


*For arcs in the middle, unitary cost (in red) and capacity are taken as infinite  
For other arcs, costs are taken as zeros.*

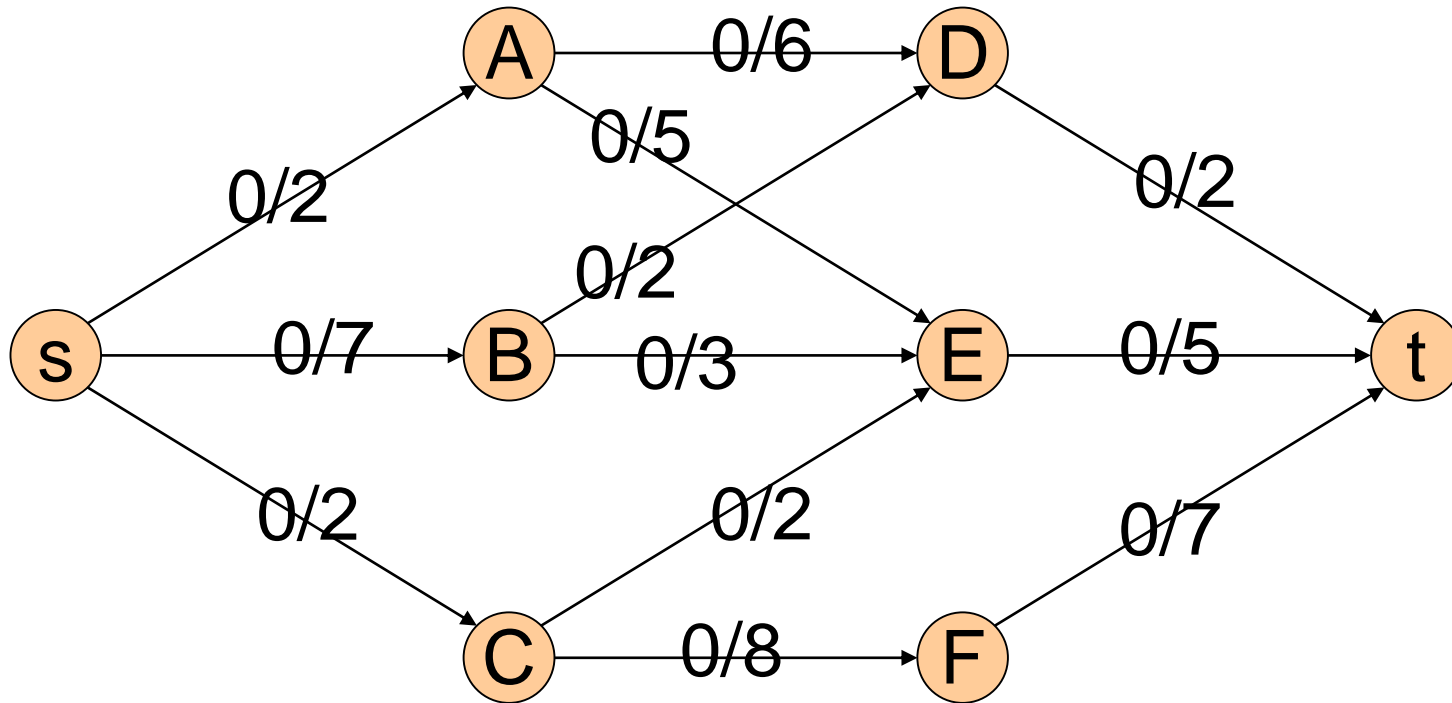
## ***Definition of the complete s-t-flow***

- > Let  $R=(G,u,s,t)$  be a transport network,  $s$ - $t$ -flow  $f$  on  $R$  is called *complete* if for any  $s$ - $t$ -path  $P=((s,v_1),(v_1,v_2),\dots,(v_{n-1},v_n),(v_n,t))$ , there exists  $a \in P$  such that  $f(a) = u(a)$ .
- Some complete flow is not necessarily maximum.
- > Construction of a complete  $s$ - $t$ -flow :
- Set  $f := 0$ .
  - Repeat
    - Choose some  $s$ - $t$ -path  $P$  such that  $\forall a \in P$  we have  $f(a) < u(a)$ .
    - If such path doesn't exist, stop.
    - Otherwise, for all  $a \in P$  do  $f(a) := f(a) + \min_{a \in P} u(a) - f(a)$ .

# Example

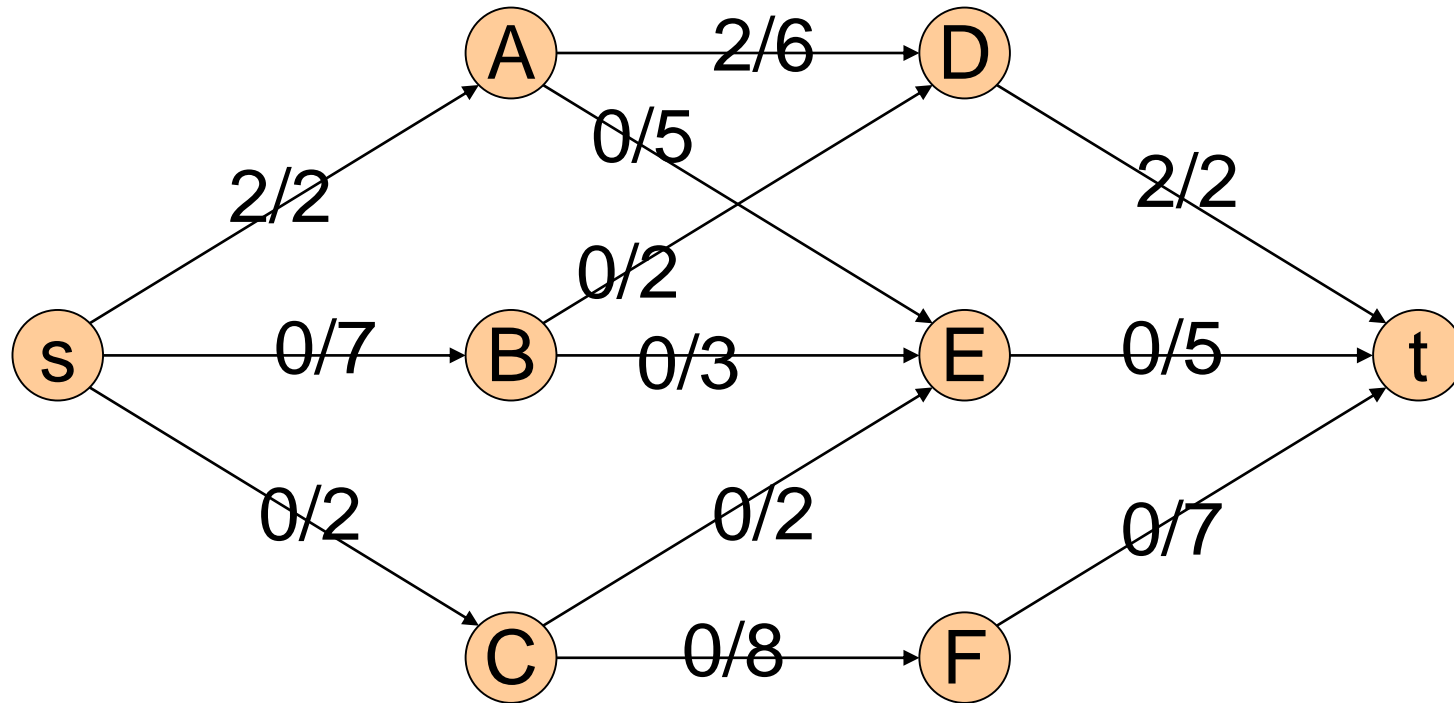


# Example



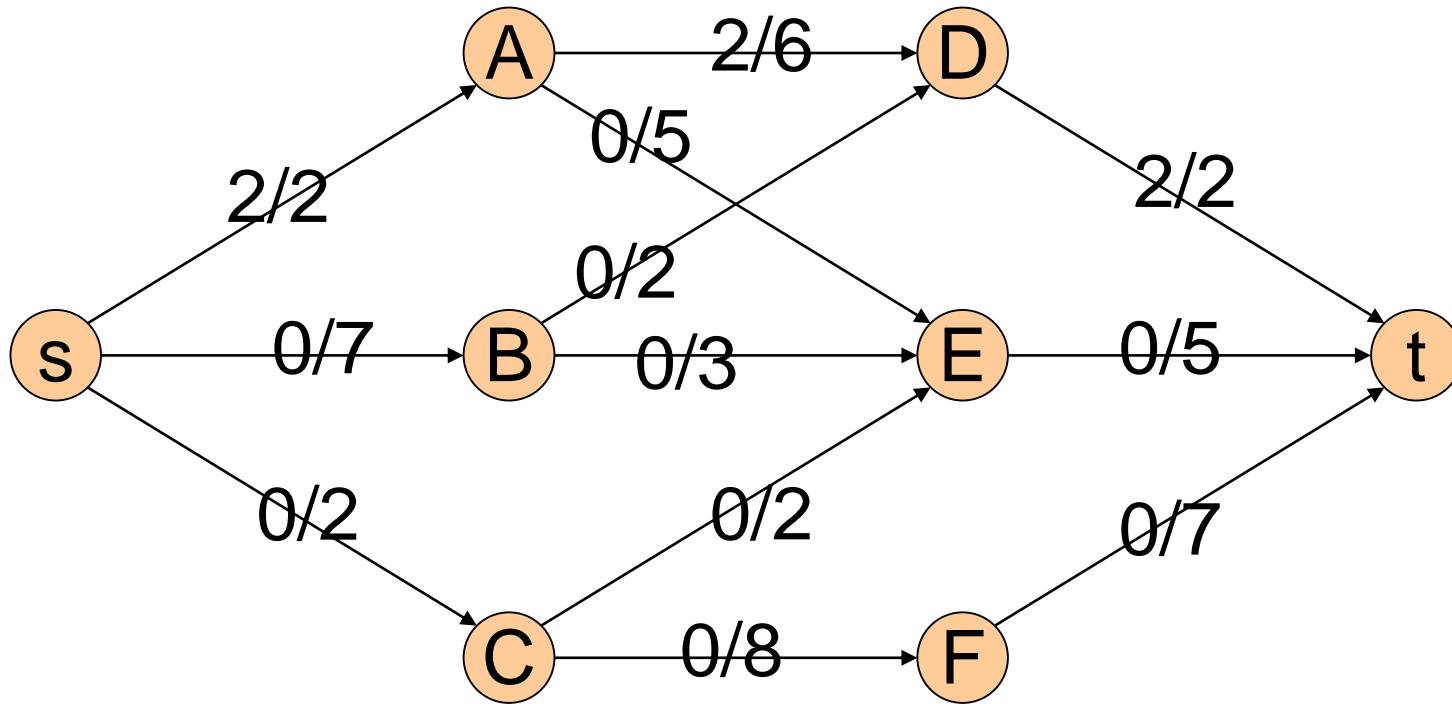
$$P = ((s,A),(A,D),(D,t)), \min_{a \in P} u(a)-f(a)=2$$

# Example



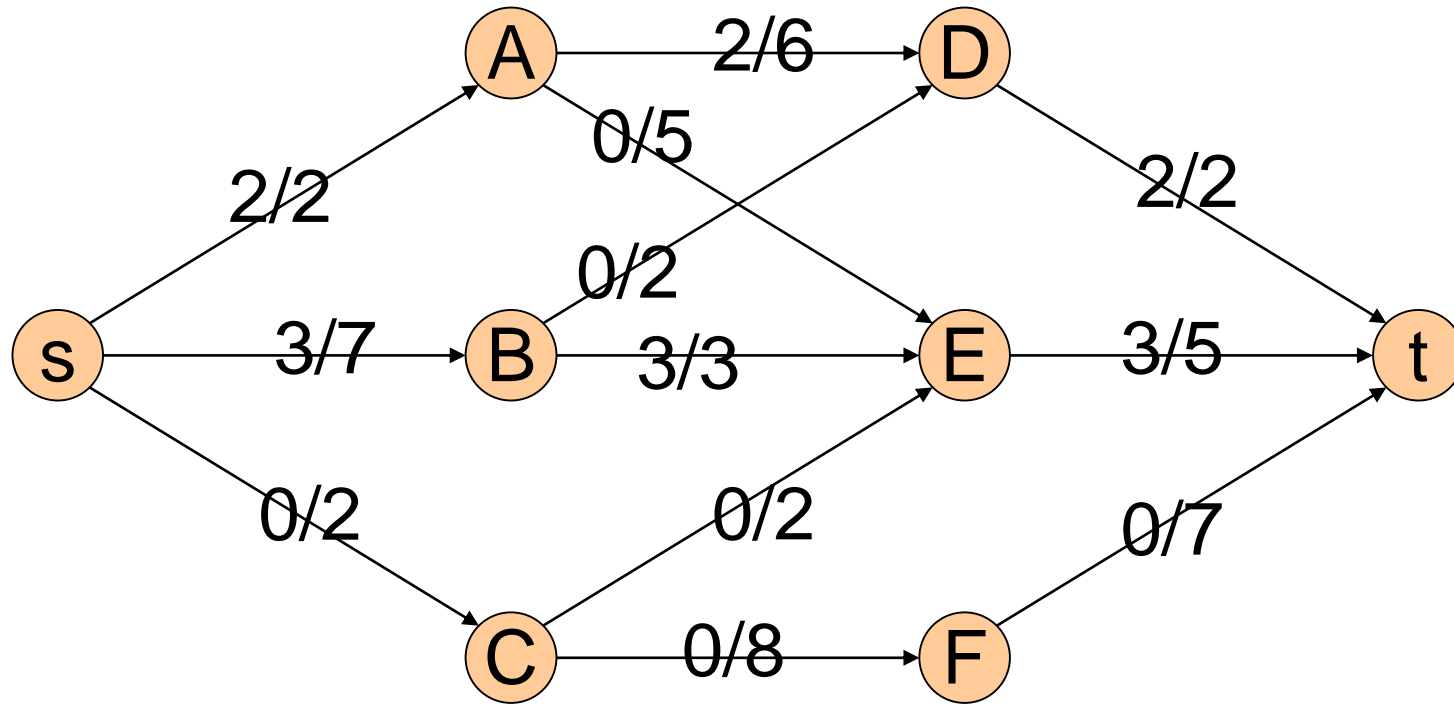


# Example

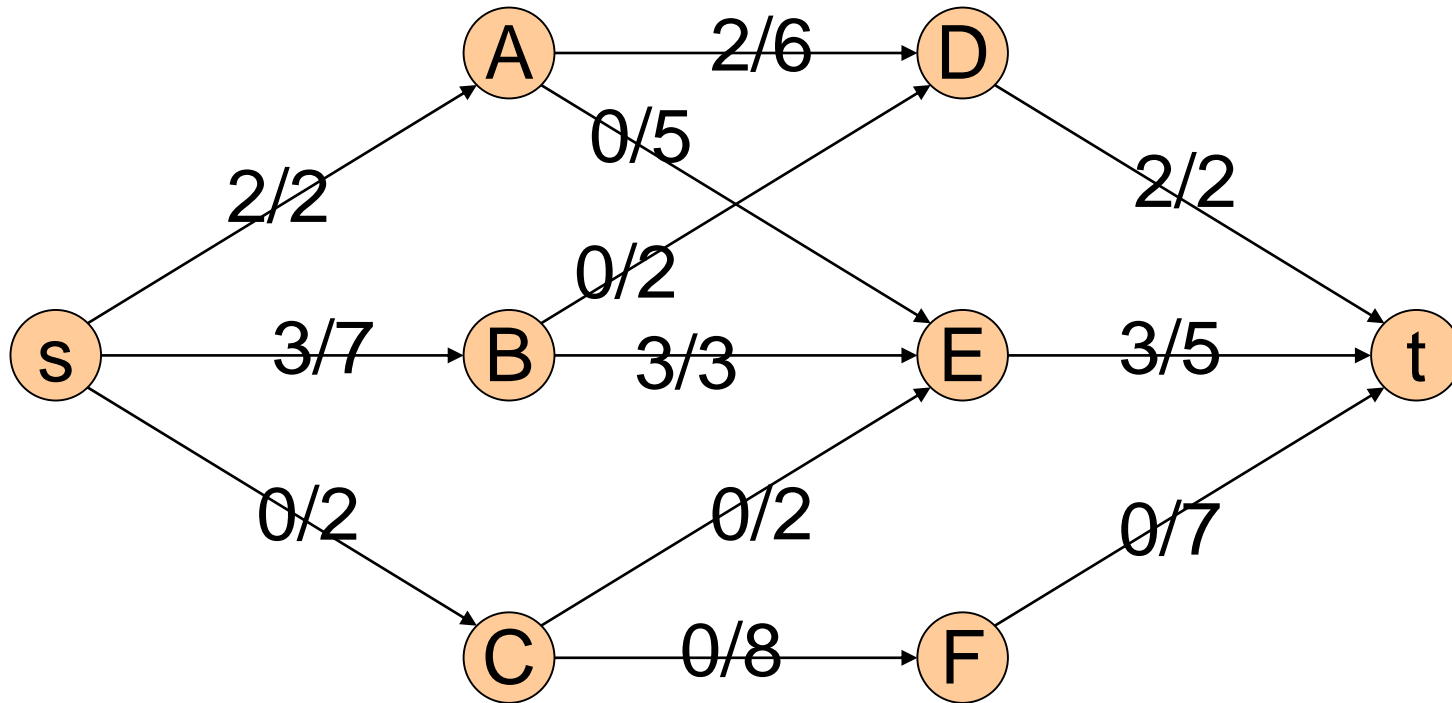


$$P = ((s,B),(B,E),(E,t)), \min_{a \in P} u(a)-f(a)=3$$

# Example

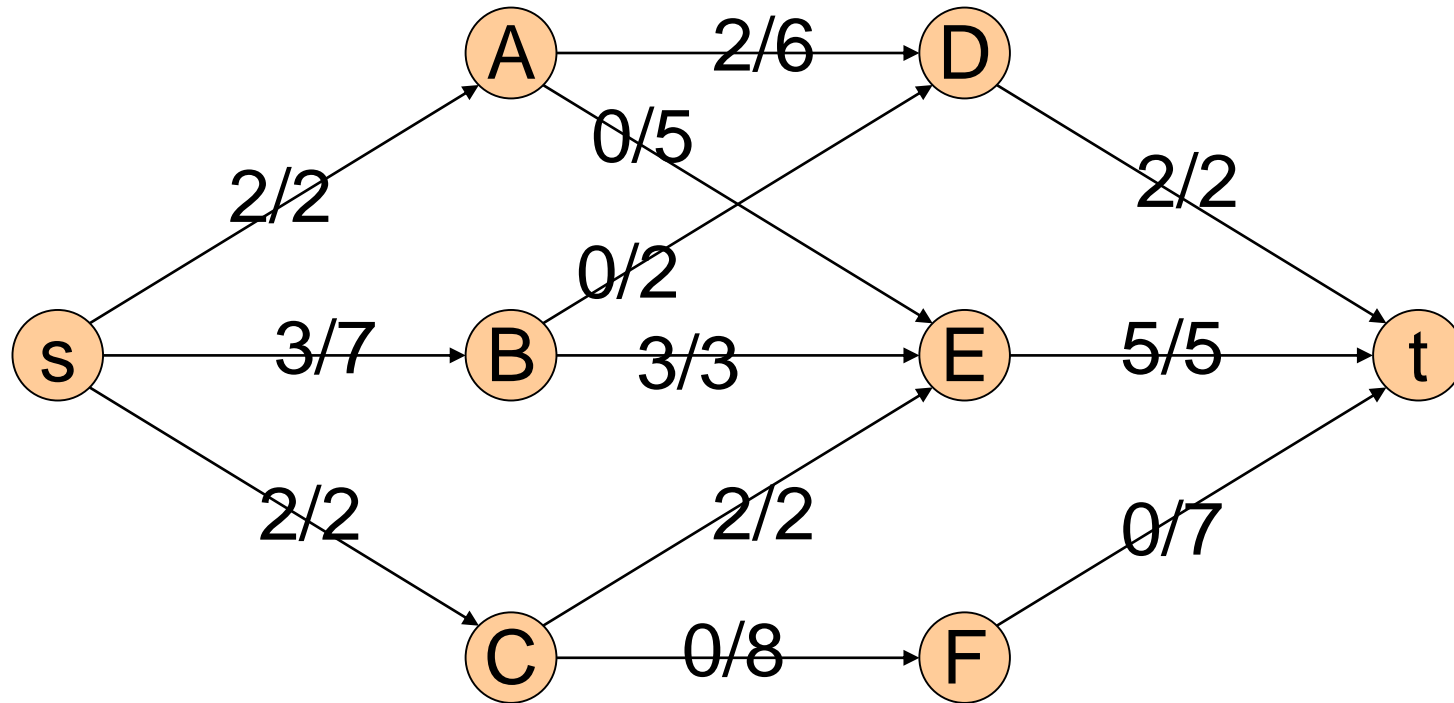


# Example



$$P = ((s,C),(C,E),(E,t)), \min_{a \in P} u(a)-f(a)=2$$

# Example



$\text{value}(f) = 7$

# The maximum $s$ - $t$ -flow problem

- > A complete flow is not necessarily a maximum one.
- > Let  $R=(G,u,s,t)$  be a transport network, the maximum  $s$ - $t$ -flow problem consists in finding some  $s$ - $t$ -flow  $f^*$  such that  $\text{value}(f^*)$  is maximum.
  - I.e., find  $f^*$  s. t. for all  $s$ - $t$ -flow  $f$  on  $R$  we have  $\text{value}(f) \leq \text{value}(f^*)$ .

# The residual graph

- > Given  $G=(V,A)$  a digraph, we let  $G'=(V,A\cup A')$  such that if  $a=(v,w)\in A$  then  $a'=(w,v)\in A'$ .
  - Remark :  $G'$  can contain parallel arcs even when  $G$  doesn't have any.
- > Given a transport network  $R=(G,u,s,t)$  and an  $s$ - $t$ -flow  $f$  on  $R$ ,  $u_f : A\cup A' \rightarrow \mathbb{R}^+$  is called the residual capacity function s. t.:
  - $u_f(a) = u(a) - f(a)$ , for all  $a\in A$ .
  - $u_f(a') = f(a)$ , for all  $a=(v,w)\in A$  and  $a'=(w,v)\in A'$ .
- > We call *residual graph associated to  $f$*  the graph
$$G_f = (V, \{a\in A\cup A' : u_f(a) > 0\}).$$

# Notion of $f$ -augmenting path

- > Let  $R=(G,u,s,t)$  be a transport network,  $f$  an  $s$ - $t$ -flow on  $R$ ,  $P$  a path on  $G_f$  and  $\gamma > 0$ , *augment*  $f$  with  $\gamma$  over  $P$  means:
- $f(a) := f(a) + \gamma$  when  $a \in A$ .
  - $f(a) := f(a) - \gamma$  when  $a' \in A'$ .
- > We call  *$f$ -augmenting path*, any  $s$ - $t$ -path in  $G_f$ .

# Ford-Fulkerson algorithm

> Input:  $R=(G,u,s,t)$  a transport network.

> Output: an  $s$ - $t$ -flow  $f$  of maximum value.

> Description:

- Set  $f := 0$ .
- Repeat:
  - Choose an  $f$ -augmenting path  $P$ .
  - If such path doesn't exist, then end ( $f$  is maximum).
  - Augment  $f$  with  $\gamma = \min_{a \in P} u_f(a)$  over  $P$ .

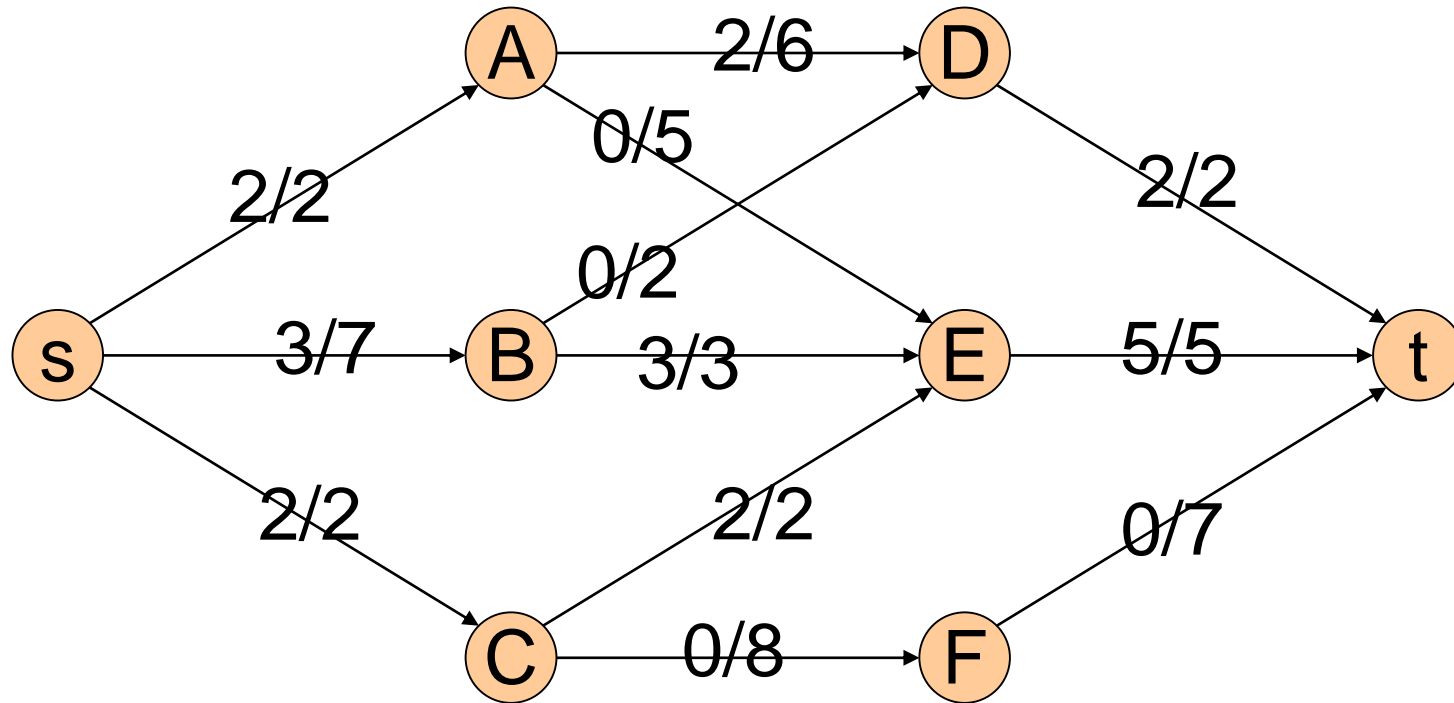


# Ford-Fulkerson algorithm

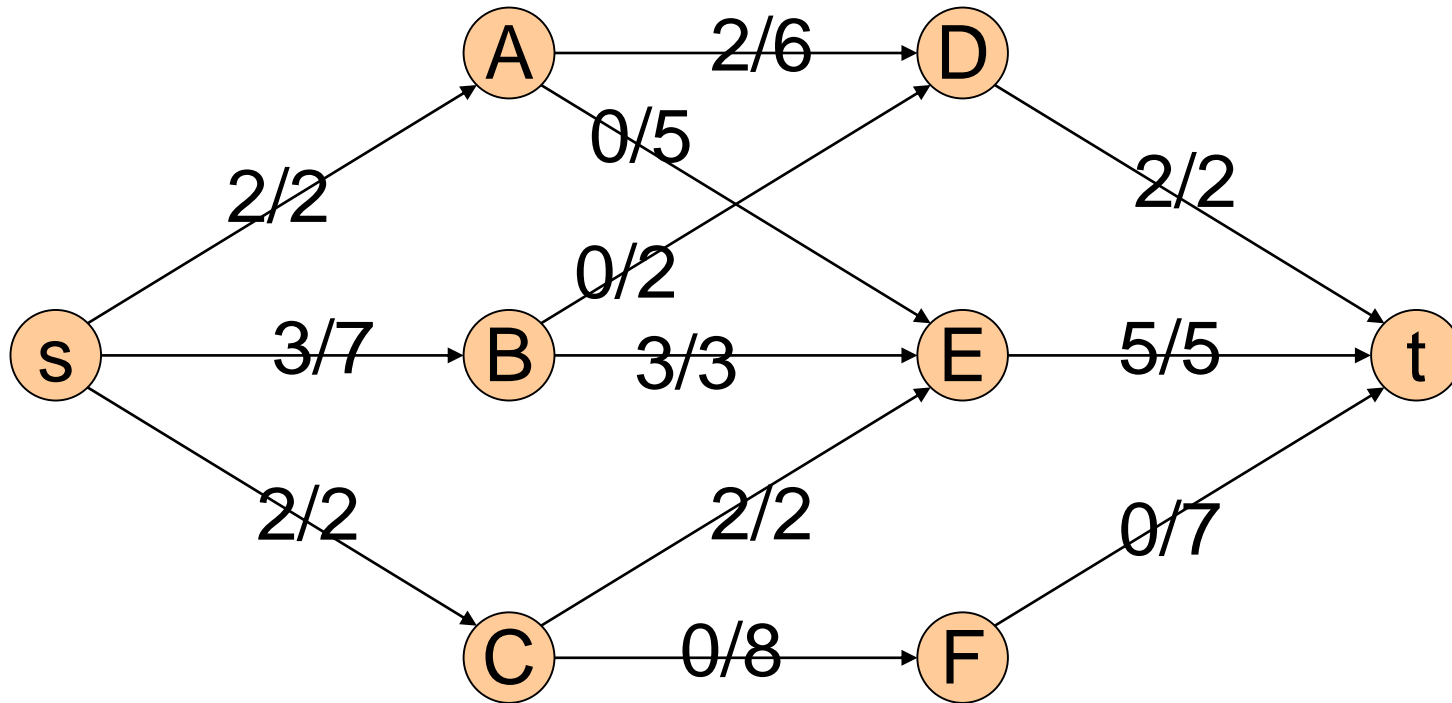
> A practical method:

- Step 1. Set  $f := 0$ ; mark  $S$ ;
- Step 2. While there is a non examined marked node  $i$  and  $t$  is not marked, do:
  - Mark all successors with residual capacities of  $i$  with  $i+$ ;
  - Mark all predecessors with positive incoming flow of  $i$  with  $i-$ ;
  - End while;
- Step 3. If  $t$  is marked, determine the augmenting path  $P$  and augment  $f$  with  $\gamma = \min_{a \in P} u_f(a)$  over  $P$ . Mark  $S$  and go back to step 2.
  - Otherwise, the flow is maximal;

## Example (previous)

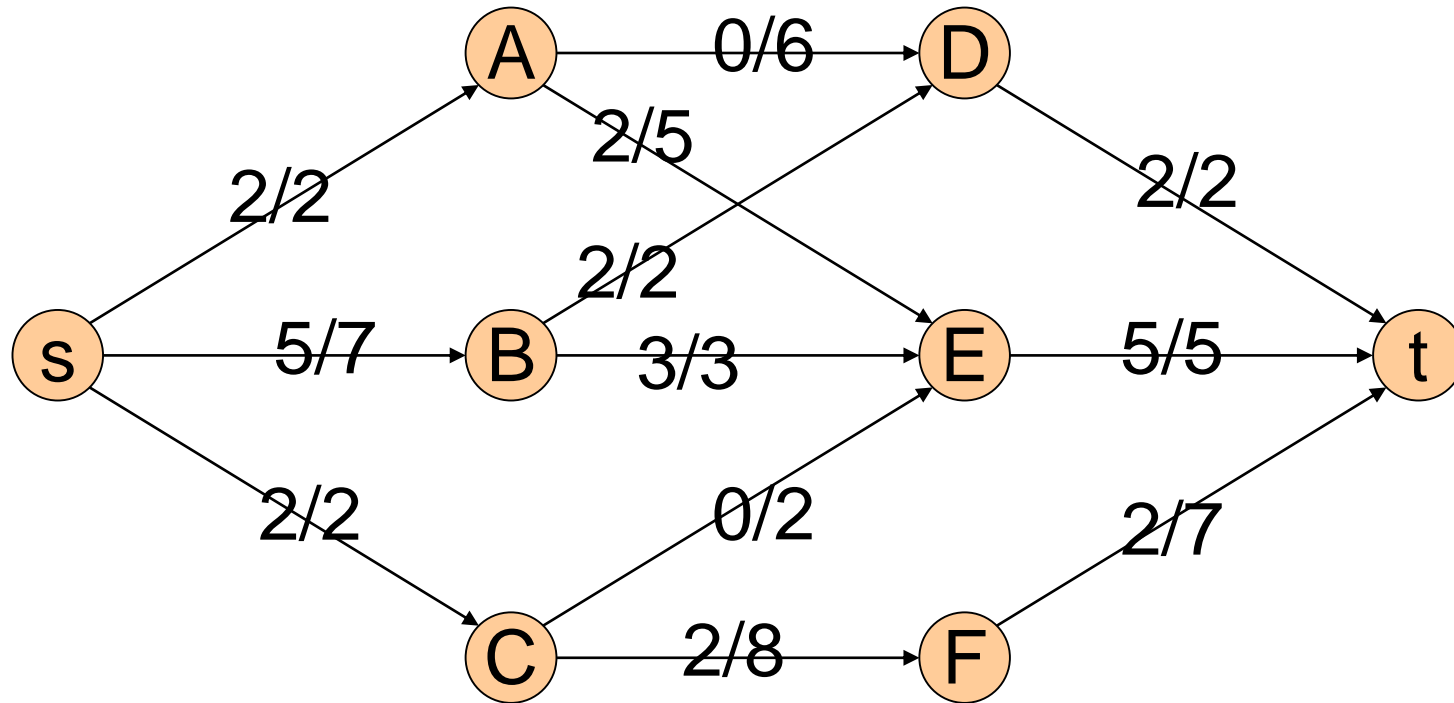


## Example (previous)



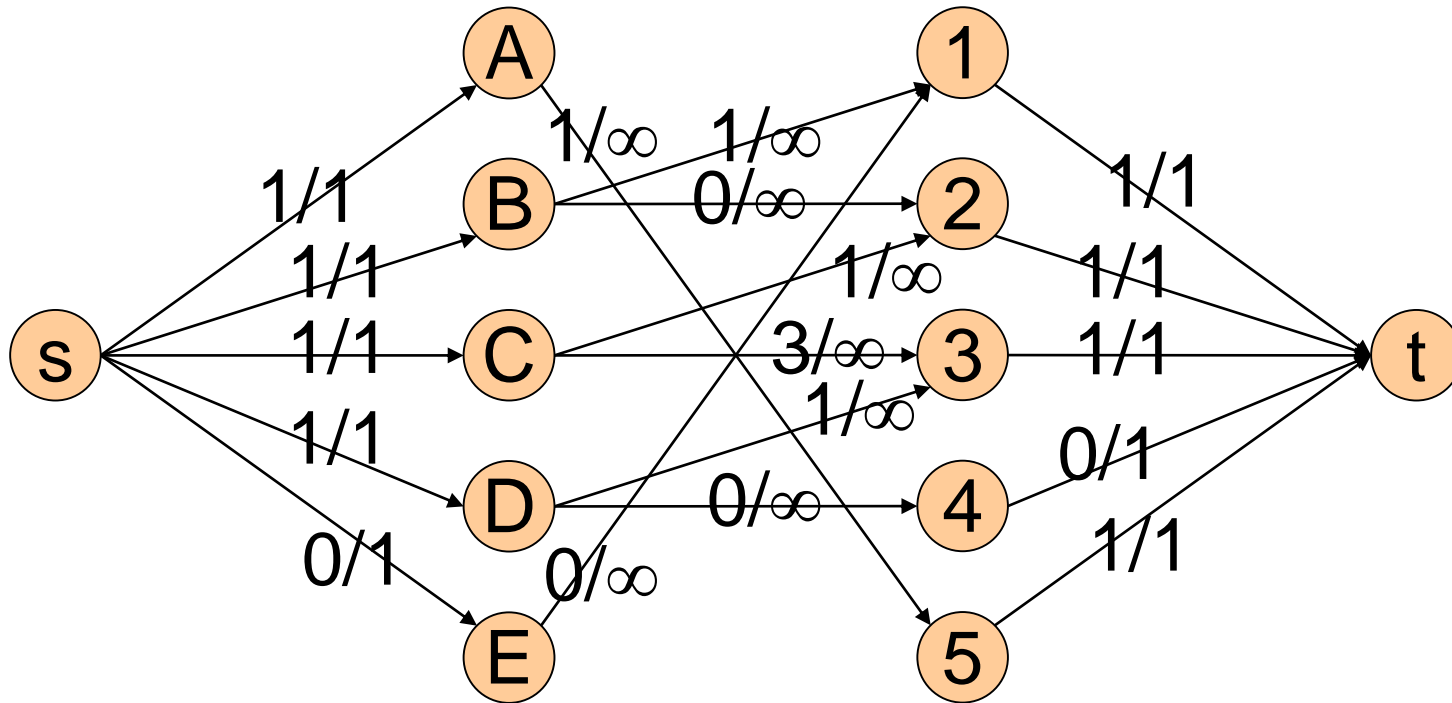
$$P = ((s,B),(B,D),(D,A),(A,E),(E,C),(C,F),(F,t)),$$
$$\min_{a \in P} u_f(a) = 2$$

## Example (previous)



$\text{value}(f) = 9$ ,  $f$  is maximum

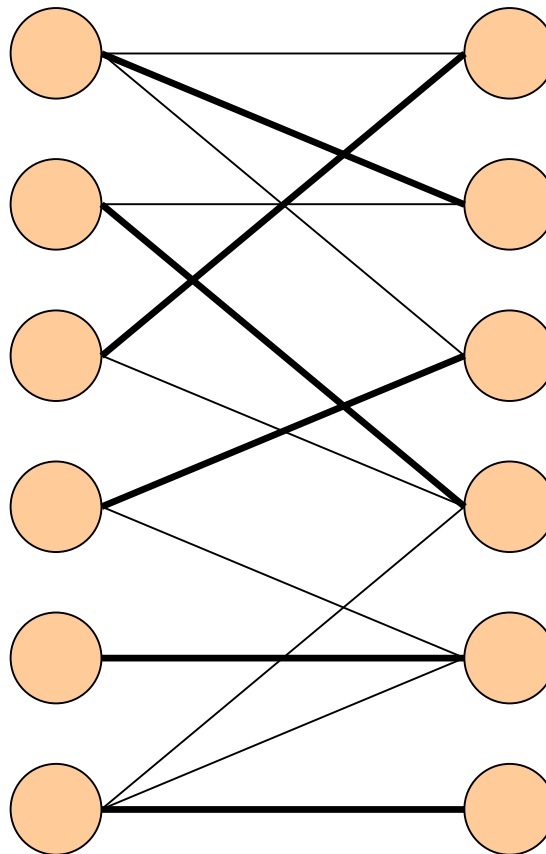
Go on ...



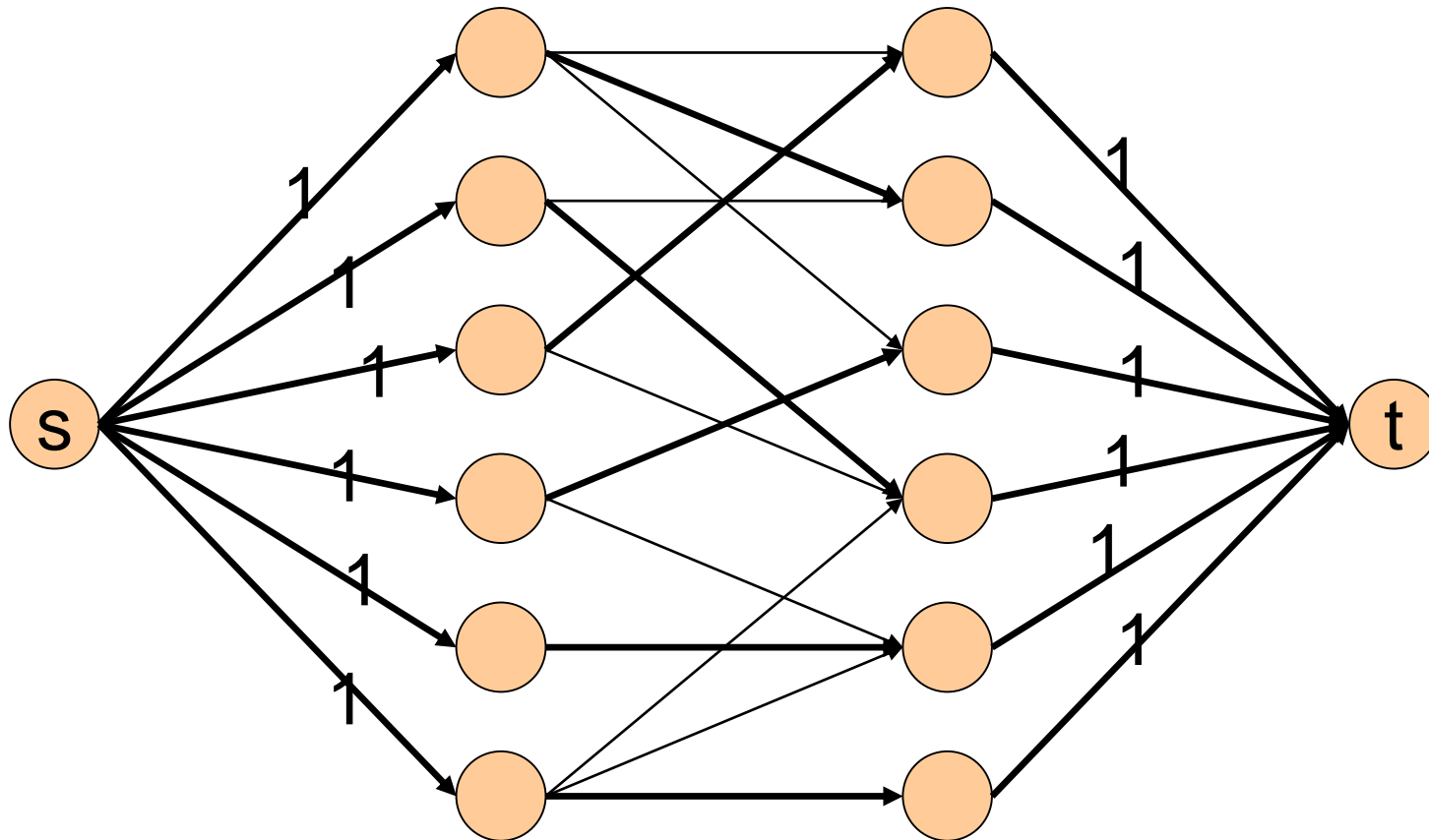
Transform the above complet flow to a maximum one

# The maximum bipartite matching

> Transform this problem to a maximum flow one.



# The maximum bipartite matching



## Lemma on generalized Kirchoff constraints

> Let  $R=(G,u,s,t)$  be a transport network and  $f$  an  $s$ - $t$ -flow in  $R$  then for all  $X \subseteq V \setminus \{s,t\}$  we have :

$$\sum_{a \in \delta^-(X)} f(a) = \sum_{a \in \delta^+(X)} f(a).$$

□



# Lemma

> Let  $R=(G, u, s, t)$  be a transport network and  $f$  an  $s$ - $t$ -flow in  $R$  then for all  $X \subseteq V$  s. t.  $s \in X$  and  $t \notin X$  we have :

(a)  $\text{value}(f) = \sum_{a \in \delta^+(X)} f(a) - \sum_{a \in \delta^-(X)} f(a)$ .

(b)  $\text{value}(f) \leq \sum_{a \in \delta^+(X)} u(a)$ .

> Proof :

(a) : similar to previous lemma.

(b) : trivial implication of (a) and of positivity of flow function ( $0 \leq f(a) \leq u(a)$ ).

□

# Theorem

> Let  $R=(G, u, s, t)$  be a transport network, an  $s$ - $t$ -flow  $f$  in  $R$  is maximum iff it doesn't exist an  $f$ -augmenting path.

> Proof :

Necessity : if such path exist, it would conduct to larger flow value, hence  $f$  is not maximum.

Sufficiency : if there is no  $f$ -augmenting path,  $t$  is not reachable (by definition) from  $s$  in  $G_f$ . Let  $Y$  be the set of reachable vertices from  $s$  in  $G_f$ . By definition of  $G_f$  we have  $f(a)=u(a)$  (because  $u_f(a)=u(a)-f(a)=0$ ) for all  $a$  of  $\delta^+_G(Y)$  and  $f(a)=0$  (because  $u_f(a')=f(a)=0$ ) for all  $a$  in  $\delta^-_G(Y)$ . The previous lemma (part (a)) implies

$$\text{value}(f) = \sum_{a \in \delta^+_G(Y)} u(a),$$

and part(b) allows to conclude.

□

# Connection to the minimum cut problem

> Let  $G=(V,A)$  be a digraph,  $X \subseteq V$  is called cut in  $G$  if  $s \in X$  and  $t \notin X$ .

- We define  $\text{capacity}(X) = \sum_{a \in \delta^+(X)} u(a)$ .

> Theorem : Let  $R=(G,u,s,t)$  be a transport network, the maximum value of  $s$ - $t$ -flow in  $R$  is equal to the minimum capacity of cuts in  $G$ .

> Proof (hint) :

For any cut  $X$ , we have  $\text{capacity}(\delta^+(X)) = \sum_{a \in \delta^+(X)} u(a) \geq \text{value}(f)$ .

On the other hand, for a maximum flow we can build a cut with the same capacity, which proves the validity of the theorem.

□

# Remarks on the integrality

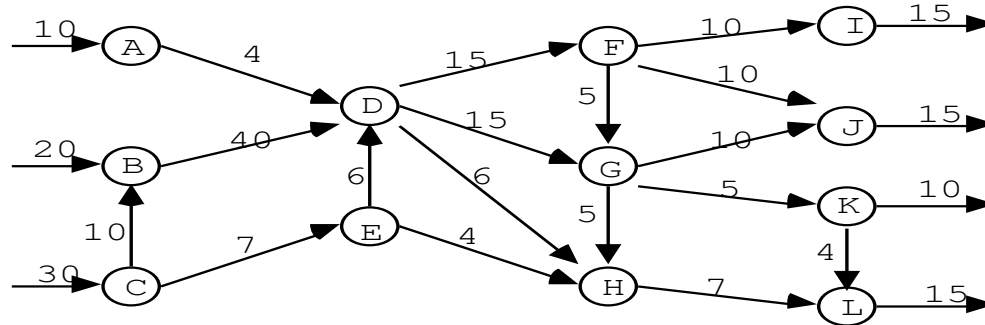
- > Corollary : let  $R=(G,u,s,t)$  be a transport network with  $u : A \rightarrow \mathbb{Z}^+$ , then there exists a maximum  $s$ - $t$ -flow with integral values and Ford-Fulkerson algorithm achieves such a flow.
- > Proof :
  - This is because the capacity function has integer values  $\gamma = \min_{a \in P} u_f(a)$ .
  -
- > Remark : the corresponding LP yields as well integral values because the associated matrix is TU (i.e., all their sub-determinants are 0, +1 or -1).

# Remarks on algorithmic aspects

- > To achieve better performances, it is convenient not to choose  $f$ -augmenting paths arbitrarily.
- > Par ex. the Edmonds-Karp algorithm suggests to choose the shortest augmenting path.
  - Theorem : The Edmonds-Karp algorithm solve the  $s$ - $t$ -flow maximum problem in  $O(m^2n)$ .
- > Other algorithms exist, for instance the Golberg-Tarjan algorithm, which runs in  $O(n^3)$ .

# A PROBLEM OF URBAN CIRCULATION

The road network which Fulkerson City must maintain is illustrated below (the capacities of the arcs represent the maximum flow in cars per hour).



- 1) Let  $N$  be the maximum number of cars per hour which can circulate through this network.
  - 1.1) Calculate  $N$ .
  - 1.2) Characterize the routes that can be created in order to increase  $N$ . By how much can we increase  $N$ ?
- 2) The local officials want to improve the circulation, increasing the number  $N$  by creating new routes. In urban areas, only the creation of a route  $HK$  and the widening of the street  $EG$  previously reserved for pedestrians are feasible. The choice will therefore have to be made between:
  - a) creating  $HK$ ; b) widening  $EG$ ; c) creating  $HK$  and widening  $EG$ .

END

# Multicommodity flows

Un multi-commodity flow  $\Phi$  is composed of several distinct flows  $\Phi^d$  for any couples  $(s^d, t^d)$ . Any node in the graph can be source or destination.

Similarly to simple flows, a multi-flow defines a function  $\Phi$  from  $U$  to  $R_+$  satisfying:

- *Capacity constraints(!)*
- *Flow conservation (!!)*
- *Flow value to satisfy/maximize(!!!)*



# Dynamic flow

- > Until now we have seen static flows, no temporal considerations have been taken into account;
- > Some flows are dynamic in time, ATM, transport...
- > Ford-Fulkerson (1958) have shown how we can transform dynamic flows to static ones.

# Transformation of a dynamic flow to a static one an example

